

Thiele Formalism: Dynamics of spin textures

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Reference: [Phys. Rev. Lett. 30, 230 \(1973\)](#)

The magnetization texture in a thin nanomagnet can be written as

$$\vec{m}(\vec{r}, t) = \vec{m}(\vec{r} - \vec{R}(t)) \quad (1)$$

where \vec{r} is in the plane normal to the thin film normal. Starting with the ansatz that the magnetization texture moves as a whole without changes in the texture allows us to write

$$\dot{\vec{m}} = -(\dot{\vec{R}} \cdot \vec{\nabla})\vec{m} \quad (2)$$

The magnetization dynamics is governed by the LLG equation

$$\dot{\vec{m}} = -\gamma \vec{m} \times \vec{H}_{\text{eff}} + \alpha \vec{m} \times \dot{\vec{m}} \quad (3)$$

which is equivalent to

$$\vec{m} \times \dot{\vec{m}} = -\gamma (\vec{m} \cdot \vec{H}_{\text{eff}})\vec{m} + \gamma \vec{H}_{\text{eff}} - \alpha \dot{\vec{m}} \quad (4)$$

Since

$$\vec{m} \cdot \dot{\vec{m}} = 0 \Rightarrow -\dot{R}_j \vec{m} \cdot \partial_j \vec{m} = 0 \quad (5)$$

and since $\dot{R}_j \neq 0$, $\vec{m} \cdot \partial_j \vec{m} = 0$.

Upon substitution of the Thiele ansatz into the LLG

$$-\vec{m} \times (\dot{\vec{R}} \cdot \vec{\nabla})\vec{m} = -\gamma (\vec{m} \cdot \vec{H}_{\text{eff}})\vec{m} + \gamma \vec{H}_{\text{eff}} + \alpha (\dot{\vec{R}} \cdot \vec{\nabla})\vec{m} \quad (6)$$

which is equivalent to

$$-\dot{R}_i \vec{m} \times \partial_i \vec{m} = -\gamma (\vec{m} \cdot \vec{H}_{\text{eff}})\vec{m} + \gamma \vec{H}_{\text{eff}} + \alpha \dot{R}_i \partial_i \vec{m} \quad (7)$$

where repeated indices are summed over. Taking dot product with $\partial_x \vec{m}$ and $\partial_y \vec{m}$, we get the two equations for the magnetization texture location in the thin magnet,

$$\begin{aligned} -\dot{R}_y (\vec{m} \times \partial_y \vec{m}) \cdot \partial_x \vec{m} &= \gamma \vec{H}_{\text{eff}} \cdot \partial_x \vec{m} + \alpha \dot{R}_i \partial_i \vec{m} \cdot \partial_x \vec{m} \\ -\dot{R}_x (\vec{m} \times \partial_x \vec{m}) \cdot \partial_y \vec{m} &= \gamma \vec{H}_{\text{eff}} \cdot \partial_y \vec{m} + \alpha \dot{R}_i \partial_i \vec{m} \cdot \partial_y \vec{m} \end{aligned} \quad (8)$$

Since $(\vec{m} \times \partial_y \vec{m}) \cdot \partial_x \vec{m} = -(\partial_x \vec{m} \times \partial_y \vec{m}) \cdot \vec{m}$ and $(\vec{m} \times \partial_x \vec{m}) \cdot \partial_y \vec{m} = (\partial_x \vec{m} \times \partial_y \vec{m}) \cdot \vec{m}$,

$$\begin{aligned} \dot{R}_y (\partial_x \vec{m} \times \partial_y \vec{m}) \cdot \vec{m} &= \gamma \vec{H}_{\text{eff}} \cdot \partial_x \vec{m} + \alpha \dot{R}_i \partial_i \vec{m} \cdot \partial_x \vec{m} \\ -\dot{R}_x (\partial_x \vec{m} \times \partial_y \vec{m}) \cdot \vec{m} &= \gamma \vec{H}_{\text{eff}} \cdot \partial_y \vec{m} + \alpha \dot{R}_i \partial_i \vec{m} \cdot \partial_y \vec{m} \end{aligned} \quad (9)$$

Integrating over the spatial dimension ($L \int d\vec{r}$) and analyzing terms one at a time.

$$\begin{aligned} \dot{R}_y L \int d\vec{r} (\partial_x \vec{m} \times \partial_y \vec{m}) \cdot \vec{m} &= \gamma L \int d\vec{r} \vec{H}_{\text{eff}} \cdot \partial_x \vec{m} + \alpha \dot{R}_i L \int d\vec{r} \partial_i \vec{m} \cdot \partial_x \vec{m} \\ -\dot{R}_x L \int d\vec{r} (\partial_x \vec{m} \times \partial_y \vec{m}) \cdot \vec{m} &= \gamma L \int d\vec{r} \vec{H}_{\text{eff}} \cdot \partial_y \vec{m} + \alpha \dot{R}_i L \int d\vec{r} \partial_i \vec{m} \cdot \partial_y \vec{m} \end{aligned} \quad (10)$$

For the first term on the right hand side, let us consider the force experienced by the magnetic texture

$$\begin{aligned}
F_j &= -\frac{dE}{dR_j} = \frac{d}{dR_j} M_s L \int d\vec{r} \vec{H}_{\text{eff}} \cdot \vec{m}(\vec{r} - \vec{R}) \\
&= M_s L \int d\vec{r} \vec{H}_{\text{eff}} \cdot \frac{d\vec{m}}{dR_j} \\
&= -M_s L \int d\vec{r} \vec{H}_{\text{eff}} \cdot \frac{d\vec{m}}{dr_j} \equiv -M_s L \int d\vec{r} \vec{H}_{\text{eff}} \cdot \partial_j \vec{m}
\end{aligned} \tag{11}$$

since the energy density is $-M_s \vec{H}_{\text{eff}} \cdot \vec{m}(\vec{r} - \vec{R})$. Therefore,

$$\gamma L \int d\vec{r} \vec{H}_{\text{eff}} \cdot \partial_j \vec{m} = -\frac{\gamma}{M_s} F_j \tag{12}$$

Consequently,

$$\begin{aligned}
\dot{R}_y \frac{M_s L}{\gamma} \int d\vec{r} (\partial_x \vec{m} \times \partial_y \vec{m}) \cdot \vec{m} &= -F_x + \alpha \frac{M_s L}{\gamma} \int d\vec{r} \partial_x \vec{m} \cdot \partial_i \vec{m} \dot{R}_i \\
-\dot{R}_x \frac{M_s L}{\gamma} \int d\vec{r} (\partial_x \vec{m} \times \partial_y \vec{m}) \cdot \vec{m} &= -F_y + \alpha \frac{M_s L}{\gamma} \int d\vec{r} \partial_y \vec{m} \cdot \partial_i \vec{m} \dot{R}_i
\end{aligned} \tag{13}$$

Using the definition for topological charge

$$Q = \frac{1}{4\pi} \int d\vec{r} (\partial_x \vec{m} \times \partial_y \vec{m}) \cdot \vec{m} \tag{14}$$

we can define the Gyrotropic vector

$$\vec{G} = \hat{z} \frac{4\pi M_s L}{\gamma} Q = G_z \hat{z} \tag{15}$$

and defining the dissipation tensor elements as

$$D_{pq} = \alpha \frac{M_s L}{\gamma} \int d\vec{r} \partial_p \vec{m} \cdot \partial_q \vec{m} \tag{16}$$

With these definitions, the equation of motion for the Skyrmion center is

$$\begin{aligned}
\dot{R}_y G_z &= -F_x + D_{xi} \dot{R}_i \\
-\dot{R}_x G_z &= -F_y + D_{yi} \dot{R}_i
\end{aligned} \tag{17}$$

Therefore in vectorial form, the equation of motion is

$$\dot{\vec{R}} \times \vec{G} = -\vec{F} + \bar{D} \dot{\vec{R}} \tag{18}$$

where \bar{D} is the dissipation tensor with elements given by D_{pq} .

A. Solution:

We can easily solve the equation of motion under the action of a linear restoring force in absence of dissipation,

$$\begin{aligned}
\dot{R}_y G_z &= k R_x \\
-\dot{R}_x G_z &= k R_y
\end{aligned} \tag{19}$$

Defining a complex variable $Z = R_x + i R_y$,

$$-i \dot{Z} G_z = k Z \Rightarrow \dot{Z} = i \omega_G Z \tag{20}$$

Laplace transforming,

$$Z(s) = \frac{Z(0)}{s - i\omega_G} \quad (21)$$

Therefore,

$$Z(t) = Z(0) \exp(i\omega_G t) \quad (22)$$

which implies

$$\begin{aligned} R_x(t) &= R_x(0) \cos \omega_G t - R_y(0) \sin \omega_G t \\ R_y(t) &= R_x(0) \sin \omega_G t + R_y(0) \cos \omega_G t \end{aligned} \quad (23)$$